

Hierarchical Galerkin methods for hyperbolic problems with parabolic asymptotics

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Main goals

Asymptotic preserving numerical schemes for hyperbolic problems.

- ▷ hyperbolic balance laws with stiff relaxation
- ▷ convergence to equilibrium and large time behaviour
- ▷ uniformly stable and asymptotic preserving numerical schemes
- ▷ a-posteriori error analysis and sensitivity calculus

Model problem

Gas transport in pipelines is modeled by

$$\partial_t \rho^e + \partial_x q^e = 0, \quad \text{on } e \in \mathcal{E}, \quad (1)$$

$$\partial_t q^e + \partial_x \rho^e = -d^e q^e, \quad \text{on } e \in \mathcal{E}, \quad (2)$$

with $d^e = d^e(\rho^e, q^e) = \lambda/(2D)|q|/\rho$ and $p(\rho) = c^2 \rho$.

Balance laws across junctions yield

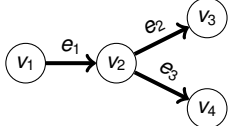
$$\rho^e(v) = \rho^{e'}(v), \quad \text{for all } e, e' \in \mathcal{E}(v), v \in \mathcal{V}_0, \quad (3)$$

$$\sum_{e \in \mathcal{E}(v)} n^e(v) q^e(v) = 0, \quad \text{for all } v \in \mathcal{V}_0. \quad (4)$$

Input/boundary condition described by pressure at the ports

$$\rho^e(v) = u_v, \quad \text{for all } v \in \mathcal{V}_\partial. \quad (5)$$

Example network:



▷ $\mathcal{V}_0 = \{v_2\}, \mathcal{V}_\partial = \{v_1, v_3, v_4\}$

▷ $\mathcal{E}(v_2) = \{e_1, e_2, e_3\}$

▷ $n^{e_1}(v_2) = 1, n^{e_2}(v_2) = -1$

Physical properties:

(P1) dissipation of energy $E = \frac{1}{2}(\|\rho\|^2 + \|q\|^2)$, i.e.

$$\frac{d}{dt} E = -(dq, q) - (q, nu)_{\mathcal{V}_\partial}$$

(P2) conservation of mass: $\frac{d}{dt} \int_{\mathcal{E}} \rho dt = \sum_{v \in \mathcal{V}_\partial, e \in \mathcal{E}(v)} n^e(v) q^e(v)$;

(P3) exponential convergence to equilibrium when $u \equiv 0$;

(P4) existence of unique steady states for the stationary problem.

Galerkin semidiscretization

Variational characterization: Any solution of (1)-(5) satisfies

$$(GD) \begin{cases} (a^e \partial_t \rho(t), \mu) + (\partial'_x q(t), \mu) & = 0, \\ (b^e \partial_t q(t), v) - (\rho(t), \partial'_x v) + (dq(t), v) & = (u(t), nv)_{\mathcal{V}_\partial}, \end{cases}$$

for all $\mu \in L^2(\mathcal{E})$ and $v \in H(\text{div}) = \{\tau: \tau^e \in H^1(e) \quad \forall e \in \mathcal{E} \text{ and (4) holds}\}$.

Conforming Galerkin discretization (GD_h) :

Find $\rho_h \in M_h \subset L^2(\mathcal{E})$ and $q_h \in V_h \subset H(\text{div})$, such that variational principle holds for all $\mu_h \in M_h$ and $v_h \in V_h$.

Results

Theorem. Assume that M_h, V_h satisfy

$$(A1_h) M_h = \partial'_x V_h$$

$$(A2_h) \{r: \partial'_x r = 0\} \subset V_h$$

$$(A3_h) 1 \in M_h$$

Then any solution of (GD_h) fulfills $(P1)-(P4)$.

Further results:

▷ mixed fem of arbitrary order satisfying $(A1_h)-(A3_h)$

▷ stability preserving time-discretization of arbitrary order possible;

▷ uniform stability and error estimates for fully discrete schemes

$$\|\rho_h^n - \rho(t^n)\| + \|q_h^n - q(t^n)\| \leq C(h^n + \Delta t^k) \quad \text{for all } n \geq 0$$

$$\|\rho_h^n - \rho_h^\infty\| + \|q_h^n - q_h^\infty\| \leq C e^{-\alpha t^n}$$

with constants C, α independent of $n, h, \Delta t$.

Structure preserving model reduction

Model reduction by Galerkin projection can be interpreted as

$$\begin{array}{ccc} PDE & \xrightarrow{(A1_h) - (A3_h)} & GD_h & \xrightarrow{(A1_H) - (A3_H)} & GD_H \\ & & \downarrow & & \downarrow \\ & & ALG & \xrightarrow{(\widehat{A1}) - (\widehat{A3})} & \widehat{ALG} \end{array}$$

Reduced model in algebraic form

$$(\widehat{ALG}) \begin{cases} V_1^T M_1 V_1 \dot{z}_1 + V_1^T G V_2 z_2 & = 0, \\ V_2^T M_2 V_2 \dot{z}_2 - V_2^T G^T V_1 z_1 + V_2^T D V_2 z_2 = V_2^T B_2 u, \end{cases}$$

Theorem (Model reduction). Assume that the coarse spaces M_H, V_H respectively projection matrices V_1, V_2 satisfy

$$(A1_H) M_H = \partial'_x V_H$$

$$(A2_H) \{v: \partial'_x v = 0\} \subset V_H$$

$$(A3_H) 1 \in M_H$$

$$(\widehat{A1}) R(M_1 V_1) = \mathcal{R}(G V_2)$$

$$(\widehat{A2}) N(G) \subset \mathcal{R}(V_2)$$

$$(\widehat{A3}) o_1 \in \mathcal{R}(V_2)$$

Then any solution of the Galerkin approximation (GD_H) and its algebraic representation \widehat{ALG} satisfies $(P1)-(P4)$.

Construction of projection matrices V_1, V_2 :

1. Create subspaces $\mathbb{W}_1, \mathbb{W}_2$ via Krylov iteration.

2. Choose finite dimensional spaces $\mathbb{Z}_1, \mathbb{Z}_2$, such that

$$\mathbb{V}_1 = \mathbb{W}_1 + \mathbb{Z}_1 \quad \text{and} \quad \mathbb{V}_2 = \mathbb{W}_2 + \mathbb{Z}_2$$

satisfy the compatibility conditions $(\widehat{A1}) - (\widehat{A3})$.

References:

▷ Egger, Kugler: *Damped wave systems on networks: Exponential stability and uniform approximations.* arXiv:1605.03066.

▷ Egger, Kugler, Liljegren-Sailer, Marheineke: *Model reduction for wave propagation on networks.* In preparation.