

Package ‘utilityFunctionTools’

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Type Package

Title P-Spline Regression for Utility Functions and Derived Measures

Description Predicts a smooth and continuous (individual) utility function from utility points, and computes measures of intensity for risk and higher order risk measures (or any other measure computed with user-written function) based on this utility function and its derivatives according to the method introduced in Schneider (2017) <<http://hdl.handle.net/21.11130/00-1735-0000-002E-E306-0>>.

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http://statweb.lsu.edu/faculty/marx/JOPS_0.1.0.tar.gz)

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|-------|--|
| bbase | <i>Constructs a B-spline basis of degree 'deg' (Code by Paul Eilers, Package JOPS, http://statweb.lsu.edu/faculty/marx/JOPS_0.1.0.tar.gz).</i> |
|-------|--|

Description

Constructs a B-spline basis of degree 'deg' (Code by Paul Eilers, Package JOPS, http://statweb.lsu.edu/faculty/marx/JOPS_0.1.0.tar.gz).

Usage

```
bbase(x, x1 = min(x), xr = max(x), ndx = 20, deg = 6)
```

Arguments

| | |
|-----|--|
| x | values for the x axis. |
| x1 | minimum value, default is the minimum value of the x-values. |
| xr | maximum value, default is maximum value of the x-values. |
| ndx | number of intervals to partition the distance between x1 and xr. |
| deg | degree of the B-spline basis. |

Value

a B-spline basis of degree deg and ndx + 1 internal knots.

Examples

```
x_finegrid <- seq(0.001, 1.0, (1.0 - 0.001) / 1000)
bbase(x_finegrid)
```

| | |
|------------------|--|
| compute_function | <i>Computes a continuous and smooth utility function from the given utility points</i> |
|------------------|--|

Description

Computes a continuous and smooth utility function from the given utility points

Usage

```
compute_function(  
  x,  
  y,  
  ids = NULL,  
  mode = 1,  
  penalty_order = 4,  
  lambda_max = 10000,  
  current_lambda = 1,  
  ndx = 20,  
  deg = 6,  
  verbose = 0  
)
```

Arguments

| | |
|----------------|---|
| x | a matrix or dataframe containing the certainty equivalents (x-values of utility points) for a given participant in each use case. |
| y | can be a vector or a matrix representing the corresponding utility values (y-values of utility points). |
| ids | a list containing the IDs of the participants. If not given, a list with IDs from 1 to n_observations will be created. |
| mode | an integer between 0, 1, 2 representing the three possible modes: multiple imputation, optimal classification or 'weak' classification. Default is optimal classification (1). |
| penalty_order | highest dimension (i.e., derivative) to penalize. Must be lower than deg. |
| lambda_max | maximum lambda used for computing the optimal lambda. It is used only in multiple imputation (mode = 0) and optimal (mode = 1). The default value is 10000. |
| current_lambda | lambda considered in the current iteration. Only used in multiple imputation (mode = 0) to create the combinations and as actual lambda value in 'weak' classification mode (mode = 2). The default value is 1. |
| ndx | number of intervals to partition the distance between the lowest and highest x-values of the utility points. |
| deg | degree of the B-spline basis. Determines the degree of the function to be estimated. If deg = 2, the estimated utility function will consist of quadratic functions. |
| verbose | shows some information while the program is running. |

Value

A smooth and continuous utility function.

Examples

```
x <- matrix(c(24.60938,34.76074,78.75,81.86035,128.5156,
             7.109375,80.4248,113.75,115.083,135.0781,
             3.828125,7.211914,8.75,124.1064,131.7969,
             1.640625,2.084961,8.75,36.94824,98.98438), nrow = 4, ncol = 5, byrow = TRUE)
y <- c(0.25, 0.375, 0.5, 0.625, 0.75)
compute_function(x, y, verbose = 1)
```

compute_higher_order_risk_preferences

Computes a continuous and smooth function according to the given utility points

Description

Computes a continuous and smooth function according to the given utility points

Usage

```
compute_higher_order_risk_preferences(
  x,
  y,
  ids = NULL,
  mode = 1,
  penalty_orders = c(4),
  ndx = 20,
  deg = 6,
  measures = c("risk-arrow-pratt", "crainich-eeckhoudt", "denuit-eeckhoudt"),
  ...,
  root_filename = NULL,
  verbose = 0
)
```

Arguments

| | |
|------|--|
| x | a matrix or dataframe containing the certainty equivalents (x-values of utility points) for a given participant in each use case. |
| y | can be a vector or a matrix representing the corresponding utility values (y-values of utility points). |
| ids | a list containing the IDs of the participants. If not given, a list with IDs from 1 to n_observations will be created. |
| mode | an integer between 0, 1, 2 representing the three possible modes: multiple imputation, optimal classification or 'weak' classification. Default is optimal classification (1). |

| | |
|----------------|--|
| penalty_orders | vector or constant that contains the derivatives that will be smoothed. The values in this vector should not be larger than 4. |
| ndx | number of intervals to partition the distance between the lowest and highest x-values of the utility points. |
| deg | degree of the B-spline basis. Determines the degree of the function to be estimated. If deg = 2, the estimated utility function will consist of quadratic functions. |
| measures | the utility based (intensity) measures to be computed. |
| ... | additional parameters for user-defined measures. |
| root_filename | filename containing the location of where the output files are going to be saved. |
| verbose | shows some information while the program is running. |

Value

A smooth and continuous function.

Examples

```
x <- matrix(c(24.60938,34.76074,78.75,81.86035,128.5156,
              7.109375,80.4248,113.75,115.083,135.0781,
              3.828125,7.211914,8.75,124.1064,131.7969,
              1.640625,2.084961,8.75,36.94824,98.98438), nrow = 4, ncol = 5, byrow = TRUE)
y <- c(0.25, 0.375, 0.5, 0.625, 0.75)
compute_higher_order_risk_preferences(x, y, mode = 1)

# could be used with root_filename argument:
# Linux
# outfile <- paste(dirname(getwd()), "/out", sep="")
# Win
# outfile <- paste(dirname(getwd()), "\\out", sep="")
compute_higher_order_risk_preferences(x, y, mode = 2, verbose = 1)
```

| | |
|------------------|---|
| compute_measures | <i>Given a set of smooth and continuous functions, computes predefined and user-defined measures.</i> |
|------------------|---|

Description

Given a set of smooth and continuous functions, computes predefined and user-defined measures.

Usage

```
compute_measures(
  x_grids,
  coeffs,
  ids = NULL,
  ndx = 20,
  deg = 6,
  measures = c("risk-arrow-pratt", "crainich-eeckhoudt", "denuit-eeckhoudt"),
  ...
)
```

Arguments

| | |
|----------|--|
| x_grids | a dataframe of vectors of x values for a smooth and continuous function. |
| coeffs | a dataframe of coefficients for a smooth and continuous function for each participant. |
| ids | a list containing the IDs of the participants. If not given, a list with IDs from 1 to n_observations will be created. |
| ndx | number of intervals to partition the distance between the lowest and highest x-values of the utility points. |
| deg | degree of the B-spline basis. Determines the degree of the function to be estimated. If deg = 2, the estimated utility function will consist of quadratic functions. |
| measures | a vector of measures to be computed. |
| ... | additional parameters for user-defined measures. |

Value

A set of measurements.

Examples

```
x <- rbind(seq(0.000002, 1.0, (1.0 - 0.000002) / 1000),
           seq(0.001, 1.0, (1.0 - 0.001) / 1000),
           seq(0.0004, 1.0, (1.0 - 0.0004) / 1000))
y <- rbind(seq(0.000002, 1.0, (1.0 - 0.000002) / 15),
           seq(0.001, 1.0, (1.0 - 0.001) / 15),
           seq(0.0004, 1.0, (1.0 - 0.0004) / 15))
compute_measures(x, y, ndx = 10, deg = 6)
# x_finegrid, coeff, ndx, deg are always there to be used
# The function should have additional unknown arguments (...) if the given parameters are not used
risk_arrow_pratt <- function(x_finegrid, coeff, ndx, deg){
  dy_rd <- derivative(x_finegrid, coeff, 1, ndx, deg)
  ddy_rd <- derivative(x_finegrid, coeff, 2, ndx, deg)
  return (-mean(ddy_rd, na.rm = TRUE) / mean(dy_rd, na.rm = TRUE))
}
measures = c("crainich-eeckhoudt", "denuit-eeckhoudt", risk_arrow_pratt)
compute_measures(x, y, ndx = 10, deg = 6, measures=measures)
```

| | |
|------------|--|
| derivative | <i>Computes the derivative of a function</i> |
|------------|--|

Description

Computes the derivative of a function

Usage

```
derivative(x, coeffs, degree = 1, ndx = 20, deg = 6)
```

Arguments

| | |
|--------|--|
| x | the x values for which the derivative should be computed. |
| coeffs | the coefficient. |
| degree | the degree of the derivative. |
| ndx | number of intervals to partition the distance between the lowest and highest x-values of the utility points. |
| deg | degree of the B-spline basis. Determines the degree of the function to be estimated. If deg = 2, the estimated utility function will consist of quadratic functions. |

Value

the derivative of the specified degree.

Examples

```
coeffs <- seq(0.000002, 1.0, (1.0 - 0.000002) / 25)
x <- seq(0.01, 1.0, (1.0 - 0.01) / 5)
derivative(x, coeffs)
```

| | |
|----------------|----------------------------|
| estimate_model | <i>Estimates the model</i> |
|----------------|----------------------------|

Description

Estimates the model

Usage

```

estimate_model(
  xi,
  yi,
  lambda = 1,
  n_penalty_dimensions = 1,
  penalty_order = 4,
  ndx = 20,
  deg = 6,
  cross_validation_mode = 0,
  return_estimate = 0,
  left_out_xi = c(),
  left_out_yi = c()
)

```

Arguments

| | |
|------------------------------------|--|
| <code>xi</code> | a vector containing the certainty equivalents (x-values of utility points) for a given participant in each use case. |
| <code>yi</code> | can be a vector or a matrix representing the corresponding utility values (y-values of utility points). |
| <code>lambda</code> | lambda is the penalization weight used to compute the initial estimate. The default value is 1. |
| <code>n_penalty_dimensions</code> | number of dimensions (i.e., derivatives) to penalize. Possible values are 1 or 2. The default value is 1. |
| <code>penalty_order</code> | highest dimension (i.e., derivative) to penalize. Must be lower than deg. |
| <code>ndx</code> | number of intervals to partition the distance between the lowest and highest x-values of the utility points. |
| <code>deg</code> | degree of the B-spline basis. Determines the degree of the function to be estimated. If <code>deg = 2</code> , the estimated utility function will consist of quadratic functions. |
| <code>cross_validation_mode</code> | determines which cross validation mode should be used. If 0, then the cross validation method is leave-one-third-out. If 1, then the cross validation method is a theoretical leave-one-out, i.e., based on a formula. The default value is 1. |
| <code>return_estimate</code> | parameter that indicates whether or not to return the (initially) estimated coefficients. Default is false. |
| <code>left_out_xi</code> | needed for cross validation: the x-values of the points that are left out for fitting the model, so that they can be predicted |
| <code>left_out_yi</code> | needed for cross validation: the y-values of the points that are left out for fitting the model, so that they can be predicted |

Value

Returns the sum of residuals of the prediction of the left-out points using cross validation. If specified, additionally returns the estimated coefficients of the utility function (in the B-spline basis).

Examples

```
x <- c(0.0000000, 0.2819824, 0.3007812, 0.4375000, 0.5231934, 0.7784882, 0.8945312, 1.0000000)
y <- c(0.0000, 0.1250, 0.2500, 0.5000, 0.6250, 0.6875, 0.7500, 1.0000)
estimate_model(x, y, .5)
```

evaluate_cross_validation

Evaluates the cross validation function.

Description

Evaluates the cross validation function.

Usage

```
evaluate_cross_validation(
  xi,
  yi,
  lambda = 1,
  n_penalty_dimensions = 1,
  penalty_order = 4,
  ndx = 20,
  deg = 6,
  cross_validation_mode = 0
)
```

Arguments

| | |
|----------------------|--|
| xi | a vector containing the certainty equivalents (x-values of utility points) for a given participant in each use case. |
| yi | can be a vector or a matrix representing the corresponding utility values (y-values of utility points). |
| lambda | lambda is the penalization weight used to compute the initial estimate. The default value is 1. |
| n_penalty_dimensions | number of dimensions (i.e., derivatives) to penalize. Possible values are 1 or 2. The default value is 1. |
| penalty_order | highest dimension (i.e., derivative) to penalize. Must be lower than deg. |
| ndx | number of intervals to partition the distance between the lowest and highest x-values of the utility points. |

| | |
|-----------------------|--|
| deg | degree of the B-spline basis. Determines the degree of the function to be estimated. If deg = 2, the estimated utility function will consist of quadratic functions. |
| cross_validation_mode | determines which cross validation mode should be used. If 0, then the cross validation method is leave-one-third-out. If 1, then the cross validation method is a theoretical leave-one-out, i.e., based on a formula. The default value is 1. |

Value

Returns, for the given utility points and (possibly default) settings, the predictive quality of the estimated utility function according to cross validation as a function of a specified penalty weight lambda.

Examples

```
x <- c(0.0000000, 0.2819824, 0.3007812, 0.4375000, 0.5231934, 0.7784882, 0.8945312, 1.0000000)
y <- c(0.0000, 0.1250, 0.2500, 0.5000, 0.6250, 0.6875, 0.7500, 1.0000)
evaluate_cross_validation(x, y, .5)
```

find_optimal_lambda *Finds an optimal penalty weight lambda given the parameters*

Description

Finds an optimal penalty weight lambda given the parameters

Usage

```
find_optimal_lambda(
  xi,
  yi,
  lambda_max = 10000,
  n_penalty_dimensions = 1,
  penalty_order = 4,
  ndx = 20,
  deg = 6,
  cross_validation_mode = 0,
  grid_dim = 5
)
```

Arguments

| | |
|----|--|
| xi | a vector containing the certainty equivalents (x-values of utility points) for a given participant in each use case. |
| yi | can be a vector or a matrix representing the corresponding utility values (y-values of utility points). |

| | |
|-----------------------|--|
| lambda_max | maximum lambda used for computing the optimal lambda. The default value is 10000. |
| n_penalty_dimensions | number of dimensions (i.e., derivatives) to penalize. Possible values are 1 or 2. The default value is 1. |
| penalty_order | highest dimension (i.e., derivative) to penalize. Must be lower than deg. |
| ndx | number of intervals to partition the distance between the lowest and highest x-values of the utility points. |
| deg | degree of the B-spline basis. Determines the degree of the function to be estimated. If deg = 2, the estimated utility function will consist of quadratic functions. |
| cross_validation_mode | determines which cross validation mode should be used. If 0, then the cross validation method is leave-one-third-out. If 1, then the cross validation method is a theoretical leave-one-out, i.e., based on a formula. The default value is 1. |
| grid_dim | dimension of the search grid for the initial grid search before the actual optimization. Default value is 5. |

Value

the optimal lambda for the given set of utility points and (possibly default) settings according to the specified cross validation method.

Examples

```
x <- c(0.0000000, 0.2819824, 0.3007812, 0.4375000, 0.5231934, 0.7784882, 0.8945312, 1.0000000)
y <- c(0.0000, 0.1250, 0.2500, 0.5000, 0.6250, 0.6875, 0.7500, 1.0000)
find_optimal_lambda(x, y)
```

| | |
|--------|--|
| tpower | <i>Truncated p-th power function. Helper function for creating the B-Spline basis (Code by Paul Eilers, Package JOPS, http://statweb.lsu.edu/faculty/marx/JOPS_0.1.0.tar.gz)</i> |
|--------|--|

Description

Truncated p-th power function. Helper function for creating the B-Spline basis (Code by Paul Eilers, Package JOPS, http://statweb.lsu.edu/faculty/marx/JOPS_0.1.0.tar.gz)

Usage

```
tpower(x, t, p)
```

Arguments

| | |
|---|--|
| x | Function value. |
| t | Point of truncation. |
| p | degree of the truncated polynomial function. |

Value

Returns a piece-wise defined basis functions for $x > t$.

Examples

```
tpower(1, 2, 3)
```

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